

Curtis Luk * Stephen Mann Computer Graphics Lab, David R. Cheriton School of Computer Science, University of Waterloo

ABSTRACT

An implicit surface is defined as the zero set of a scalar function over 3-space. Sign of implicit function determines whether a point is inside or outside the implicit surface:

$$f(P) \begin{cases} = 0 \ P \text{ is on the surface.} \\ < 0 \ P \text{ is inside the surface.} \\ > 0 \ P \text{ is outside the surface.} \end{cases}$$

An algebraic function is an implicit function where the function is polynomial. By using an A-patch representation of algebraic curves and surfaces, we are able to identify regions in which the curve/surface does not lie, and efficiently tessellate the curve/surface in the regions in which it does lie.

A-PATCHES

Bivariate Bernstein polynomials:

$$B^{n}_{\vec{i}}(P) = \binom{n}{\vec{i}} p_{0}^{i_{0}} p_{1}^{i_{1}} p_{2}^{i_{2}},$$

where $\vec{i} = (i_0, i_1, i_2)$ with $i_0, i_1, i_2, \ge n$ and $i_0 + i_1 + i_2 = n$, and where (p_0, p_1, p_2) are the Barycentric coordinates.

An A-patch weights scalar values with Bernstein basis:

$$F(P) = \sum_{\vec{i}} c_i B^n_{\vec{i}}(P).$$

A-patches coefficients separated by sign:



These observations lead to the following algorithm for tessellating algebraic surfaces:

Tessellating Algebraic Curves and Surfaces Using A-Patches

ADVANTAGES OF A-PATCHES

• Separation guarantees that a single sheet of the algebraic curve passes through triangle.

• Single sheet give means of tessellating:

Root find along lines from corner to opposite edge



CURVES

• Make an initial triangular over the region of interest.

• For each triangle,

-Convert the algebraic to Bernstein-Bézier representation for that triangle.

- Test the coefficients:

*If all of same sign, curve/surface does not pass through

* If in A-patch format, tessellate

* Otherwise, subdivide the triangle and repeat the process.







Idea for surfaces is similar:

- Tetrahedralize space
- All positive/negative, no surface
- A-patch format: tessellate
- Mixed coefficients: 12-to-1 subdivision

• Bernstein form of algebra within each tetrahedron